

A Whirlwind Tour of Quantum Error Correction (with some emphasis on Bosonic codes)

Ronak Ramachandran

University of Texas at Austin

June 28, 2022

Disclaimer

This slide deck is a bit messy since it was cobbled together from multiple sources last minute. If you're reading this to learn, and feel something major is missing, please email [ronak dot ramachandran at gmail dot com](mailto:ronak.dot.ramachandran@gmail.com) with any questions you have.

Outline of talk

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory
- 3 Stabilizer formalism: stabilizer codes
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

Table of Contents

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory
- 3 Stabilizer formalism: stabilizer codes
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

What is a code?

Definition

A **code** of block length n over an alphabet Σ is a subset of Σ^n . Typically, we will use q to denote $|\Sigma|$.

Definition

The **dimension** of a code $C \subseteq \Sigma^n$ is given by $k := \log_q(|C|)$

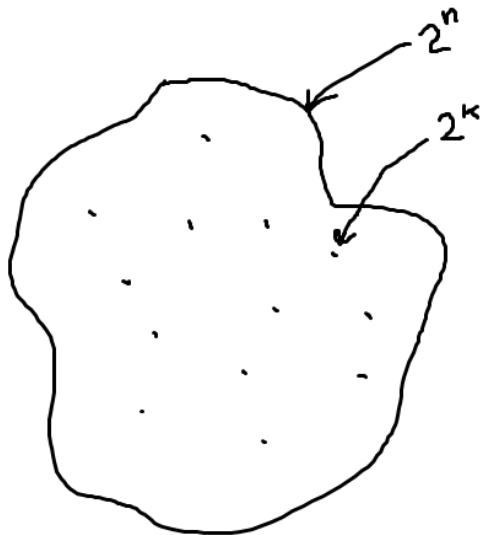
Definition

The **rate** of a code with block length n and dimension k is $R := \frac{k}{n}$

Source: GRS Coding Theory Textbook

In the case of binary codes...

$$\Sigma = \{0, 1\}, \Sigma^n = \{0, 1\}^n, k = \log_2(|C|)$$



Distance

Definition

Given two vectors $u, v \in \Sigma^n$, the **Hamming distance** between u and v , denoted by $\Delta(u, v)$, is the number of positions in which u and v differ.

Definition

Let $C \subseteq \Sigma^n$. The minimum distance (or just **distance**) of C , denoted $\Delta(C)$ (or just d), is defined to be $\Delta(C) = \min_{c_1 \neq c_2 \in C} \Delta(c_1, c_2)$.

Definition

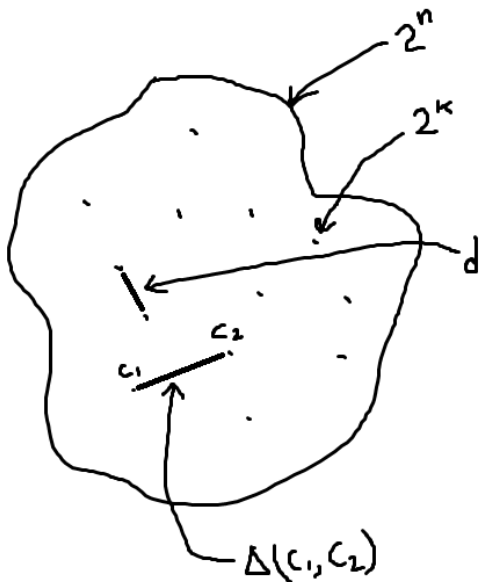
The **relative distance** of a code is given by $\delta := \frac{d}{n}$.

Codes: Block length, dimension, and distance, $[n, k, d]$.

Families of codes: rate and distance $[R, \delta]$.

Source: GRS Coding Theory Textbook

And that looks something like...

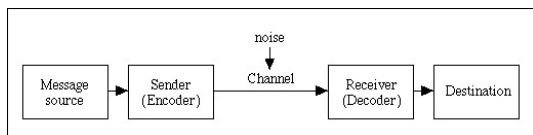


The repetition code

$$C = \{000, 111\}$$

$n = 3$, $k = 1$, $d = 3$, so we say this is a $[3, 1, 3]$ code.

I don't see any errors...



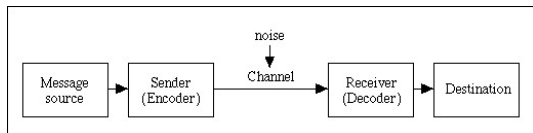
Definition

Let $C \subseteq \Sigma^n$. An equivalent description of the code C is an injective mapping $E : [|C|] \rightarrow \Sigma^n$ called the **encoding function**.

Definition

Let $C \subseteq \Sigma^n$ be a code. A mapping $D : \Sigma^n \rightarrow [|C|]$ is called a decoding function for C .

The repetition code is SECDED



Imagine noise in the form of bit flips.

The $[3, 1, 3]$ repetition code $C = \{000, 111\}$ can correct 1 error and can detect 2

Single Error Correcting, Double Error Detecting (SECDED)

In general, a code with distance d can correct $\frac{d-1}{2}$ errors and detect $d - 1$ errors.

$$\Sigma = \{0, 1\}.$$

If $x, y \in C$, then $x \oplus y \in C$.

Note this implies $x \oplus x = 0 \in C$.

Additionally, if $\Delta(x, y) = d$ (the minimum distance), then $x \oplus y \in C$ and $|x \oplus y| = d$.

The above implies d is the weight of the minimum weight codeword.

Generator Matrices and Parity Check Matrices

A linear binary code can always be specified by a generator matrix and parity check matrix.

Example: The $[7, 4, 3]$ Hamming code. (Can correct 1 error.)

$$G = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix} \quad H = \begin{bmatrix} 1 & 1 & 0 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Encoder: given $x \in \{0, 1\}^4$ (as a row vector), $xG \in C$

Detect error: $Hc^T = 0$ iff $c \in C$. Hc^T is called the **syndrome**.

Correct error: find the column of H matching the syndrome.

Table of Contents

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory**
- 3 Stabilizer formalism: stabilizer codes
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

Overview of this section

Def'n of a group, examples

Action of a group G on a set X

What stabilizers are in group theory

Action of Pauli gates (a group) on quantum states (a set)

The stabilizer formalism

Definition

A **group** is a set G together with a binary operation \cdot on G such that

(Def'n of "binary operation on G ") $\forall a, b \in G, a \cdot b \in G$

(Identity) $\exists 1 \in G$ such that $\forall a \in G, 1 \cdot a = a \cdot 1 = a$

(Associativity) $\forall a, b, c \in G, a \cdot (b \cdot c) = (a \cdot b) \cdot c$

(Inverses) $\forall a \in G, \exists b \in G$ such that $a \cdot b = 1$. Such b is denoted a^{-1} .

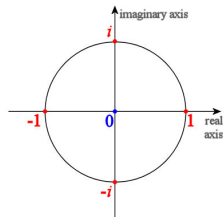
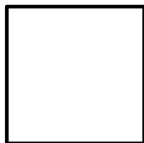
Cheat-sheet version:

$ab \in G, 1a = a1 = a, a(bc) = (ab)c, aa^{-1} = a^{-1}a = 1$.

"Closed under \cdot with an identity, associativity, and inverses."

An example group: C_4

“The cyclic group of order 4” - rotational symmetries on a square.



$C_4 = \{1, x, x^2, x^3\} = \langle x \rangle \leftarrow$ we say x is a **generator** of C_4 .

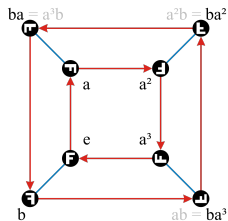
$C_4 = \{1, i, -1, -i\}$.

$C_4 = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$.

$\mathbb{Z}/4\mathbb{Z} = \mathbb{Z}_4 = \{0, 1, 2, 3\}$, Group operation: $+$ (“additive” group).

Second example: D_4

“The dihedral group of order 4” - symmetries on a square including rotations and reflections.



	ϵ	σ	σ^2	σ^3	τ	$\sigma\tau$	$\sigma^2\tau$	$\sigma^3\tau$
ϵ	ϵ	σ	σ^2	σ^3	τ	$\sigma\tau$	$\sigma^2\tau$	$\sigma^3\tau$
σ	σ	σ^2	σ^3	ϵ	$\sigma^3\tau$	τ	$\sigma\tau$	$\sigma^2\tau$
σ^2	σ^2	σ^3	ϵ	σ	$\sigma^2\tau$	$\sigma^3\tau$	τ	$\sigma\tau$
σ^3	σ^3	ϵ	σ	σ^2	$\sigma\tau$	$\sigma^2\tau$	$\sigma^3\tau$	τ
τ	τ	$\sigma\tau$	$\sigma^2\tau$	$\sigma^3\tau$	ϵ	σ	σ^2	σ^3
$\sigma\tau$	$\sigma\tau$	$\sigma^2\tau$	$\sigma^3\tau$	τ	σ^3	ϵ	σ	σ^2
$\sigma^2\tau$	$\sigma^2\tau$	$\sigma^3\tau$	τ	$\sigma\tau$	σ^2	σ^3	ϵ	σ
$\sigma^3\tau$	$\sigma^3\tau$	τ	$\sigma\tau$	$\sigma^2\tau$	σ	σ^2	σ^3	ϵ

$D_4 = \{1, x, x^2, x^3, y, xy, x^2y, x^3y\} = \langle x, y \rangle$, where $yx = x^{-1}y$.

Note $yx = x^{-1}y = x^3y \neq xy$ (D_4 is non-abelian).

Homomorphisms: 'embedding one group into another'

Definition

A **homomorphism** between two groups (G, \cdot) and $(P, *)$ is a function $\varphi : G \rightarrow P$ such that $\varphi(g \cdot h) = \varphi(g) * \varphi(h)$.

Example: For any groups G and P , $\varphi(g) = 1_P$ is a valid homomorphism. (The trivial homomorphism.)

Definition

For any groups G and P , the product group is given by $G \times P = \{(g, p) \mid g \in G, p \in P\}$ with the group operation $(g, p) \cdot (h, q) = (gh, pq)$.

Like a tensor product.

Group G acting on a set X

“A homomorphism from G to $\text{Perm}(X)$.”

$$\alpha : G \times X \rightarrow X$$

$$\alpha(e, x) = x$$

$$\alpha(g, \alpha(h, x)) = \alpha(gh, x)$$

$$g \rightarrow [\sigma_g : X \rightarrow X]$$

$$\sigma_e(x) = x$$

$$\sigma_g(\sigma_h(x)) = \sigma_{gh}(x)$$

$$g \rightarrow [g : X \rightarrow X]$$

$$e(x) = x$$

$$g(h(x)) = gh(x)$$

$$ex = x$$

$$g(hx) = (gh)x$$

Group G acting on a set X

$C_4 = \{1, x, x^2, x^3\}$ acting on a toothpick.

Toothpick has two states: horizontal and vertical, $X = \{ |, - \}$.

$$1(|) = |, 1(-) = -.$$

$$x(|) = -, x(-) = |.$$

$$x^2(|) = |, x^2(-) = -.$$

$$x^3(|) = -, x^3(-) = |.$$

Definition

We say $g \in G$ **stabilizes** $x \in X$ iff $gx = x$.

Definition

The **stabilizer subgroup** of G with respect to $x \in X$ is

$$G_x = \{g \in G \mid gx = x\}.$$

The stabilizers of $|$ are 1 and x^2 .

The Pauli group

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

16 element group:

$$P_1 = \langle X, Y, Z \rangle = \{\pm I, \pm iI, \pm X, \pm iX, \pm Y, \pm iY, \pm Z, \pm iZ\}.$$

Properties:

$$X^2 = Y^2 = Z^2 = 1$$

$$XY = iZ$$

$$YZ = iX$$

$$ZX = iY$$

$$YX = -iZ$$

$$ZY = -iX$$

$$XZ = -iY$$

The n -qubit Paulis form a group P_n of order 4×4^n .

For instance, P_2 has $4 \times 16 = 64$ elements. Examples: XI and $-iZZ$.

At the same time, P_n only has $3n$ generators.

For instance, $P_2 = \langle XI, YI, ZI, IX, IY, IZ \rangle$.

We can have the n -qubit Pauli group act on the set of n -qubit states.

The single qubit case

The states stabilized by P_1 are very special:

I stabilizes all

$-I$ stabilizes none

$$Z|0\rangle = |0\rangle$$

$$X|+\rangle = |+\rangle$$

$$Y|i\rangle = |i\rangle$$

$$-Z|1\rangle = |1\rangle$$

$$-X|-\rangle = |-\rangle$$

$$-Y|-i\rangle = |-i\rangle$$

These are the axes of the Bloch sphere.

The stabilizer formalism

Paraphrasing a bit: “The key idea of the stabilizer formalism is to represent a quantum state $|\psi\rangle$, not by a vector of amplitudes, but by a stabilizer group, consisting of unitary matrices that stabilize $|\psi\rangle$. At first stabilizers seem worse than amplitude vectors, since they require about 2^{2n} parameters to specify instead of about 2^n . Remarkably, though, a large and interesting class of quantum states can be specified uniquely by much smaller stabilizer groups—specifically, the intersection of $\text{Stab}(|\psi\rangle)$ with the Pauli group.”

Theorem 1 *Given an n -qubit state $|\psi\rangle$, the following are equivalent:*

- (i) $|\psi\rangle$ can be obtained from $|0\rangle^{\otimes n}$ by CNOT, Hadamard, and phase gates only.*
- (ii) $|\psi\rangle$ can be obtained from $|0\rangle^{\otimes n}$ by CNOT, Hadamard, phase, and measurement gates only.*
- (iii) $|\psi\rangle$ is stabilized by exactly 2^n Pauli operators.*
- (iv) $|\psi\rangle$ is uniquely determined by $S(|\psi\rangle) = \text{Stab}(|\psi\rangle) \cap \mathcal{P}_n$, or the group of Pauli operators that stabilize $|\psi\rangle$.*

The Gottesman-Knill Theorem

Theorem

Any stabilizer circuit—that is, a quantum circuit consisting solely of CNOT, Hadamard, and phase gates—can be simulated efficiently on a classical computer. See paper.

Table of Contents

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory
- 3 Stabilizer formalism: stabilizer codes**
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

Quantum Error Correcting Codes

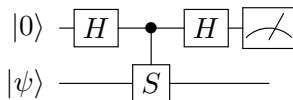
In general, specifying a Quantum Error Correcting Code (QECC) requires 4 steps:

1. Define an error model
2. Specify a codespace through stabilizing operations (syndrome measurements)
3. Show how to perform a universal set of gates on encoded states
4. Show how to prepare and decode codestates.

Stabilizer Codes

Error model: Pauli errors of a certain weight (aka k -qubit bit flips or phase flips). Actually can correct more than just these - syndrome measurements discretize errors.

Codespace: For k dimensional codespace, pick an abelian Pauli subgroup with $n - k$ generators. Make these your stabilizing operations. Perform syndrome measurements:



Gates, encoding, and decoding vary from code to code.

Example: The Steane Code

Click to go to the Steane Code Wiki

Table of Contents

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory
- 3 Stabilizer formalism: stabilizer codes
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

Fock states (Number states)

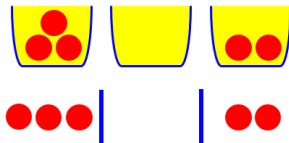
The Fock basis: list of excitation numbers

Excitation numbers can refer to the discrete energy levels of a list of oscillators or the count of photons in a list of modes

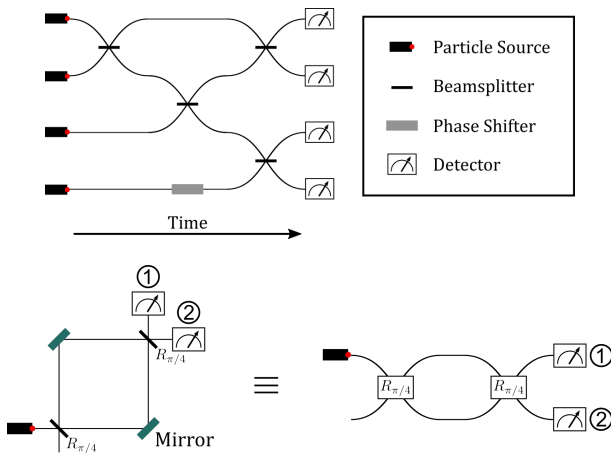
Example: 3 photons in 2 modes.

Basis states: $|3, 0\rangle$, $|2, 1\rangle$, $|1, 2\rangle$, $|0, 3\rangle$.

In general, for n photons in m modes, Hilbert space has dimension $\binom{n+m-1}{n}$



Linear optical networks



How do $m \times m$ beamsplitters translate to $M \times M$ unitaries?

Go to paper in progress + wiki for more on these.

Table of Contents

- 1 Classical error correction: linear binary codes
- 2 An unnecessary detour into group theory
- 3 Stabilizer formalism: stabilizer codes
- 4 Bosonic quantum computing: Fock-basis codes
- 5 Continuous Variable (CV) quantum computing: GKP codes

Overview of this section

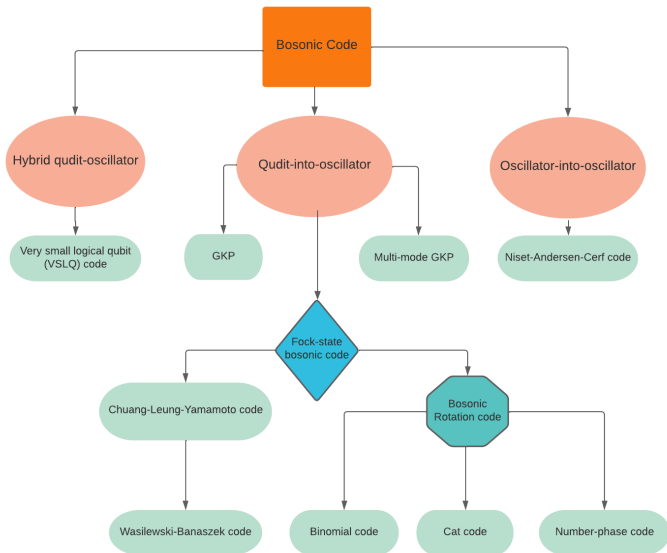
From Qubits to Qudits to CV

The Wigner Function

The GKP Code

Applications

Bird's Eye View of Bosonic Codes



Qubits and Qudits

Qubits have 2 basis states: $|0\rangle$ and $|1\rangle$

$$X|0\rangle = |1\rangle, X|1\rangle = |0\rangle$$

$$Z|0\rangle = |0\rangle, Z|1\rangle = -|1\rangle$$

$X : |n\rangle \mapsto |n+1\rangle$, with addition in \mathbb{F}_2

$Z : |n\rangle \mapsto \omega^n |n\rangle$, where $\omega = e^{2\pi i/2} = -1$

Qudits have d basis states: $|0\rangle, |1\rangle, |2\rangle, \dots, |d-1\rangle$

$X_d : |n\rangle \mapsto |n+1\rangle$, with addition in \mathbb{F}_d

$Z_d : |n\rangle \mapsto \omega^n |n\rangle$, where $\omega = e^{2\pi i/d}$

These “Shift” and “Clock” operators generalize Pauli X and Z

The Fourier Conjugate Basis

For qubits: $H = \text{QFT}_2$

Conjugate basis $H |0\rangle = |+\rangle$ and $H |1\rangle = |-\rangle$

For qudits, use:

$$|\omega^n\rangle := \text{QFT}_d |n\rangle = \frac{1}{\sqrt{d}} \sum_{m=0}^{d-1} \omega^{n \cdot m} |m\rangle$$

“Position” basis: $|0\rangle, |1\rangle, |2\rangle, \dots, |d-1\rangle$

“Momentum” basis: $|\omega^0\rangle, |\omega^1\rangle, |\omega^2\rangle, \dots, |\omega^{d-1}\rangle$

Note that $Z_d |\omega^n\rangle = |\omega^{n+1}\rangle$ and $X_d |\omega^n\rangle = \omega^{-n} |\omega^n\rangle$

Quadratures

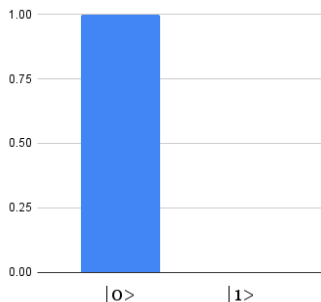
Quadratures \equiv Fourier conjugate bases

Can plot marginal probability distributions for a given state $|\psi\rangle$

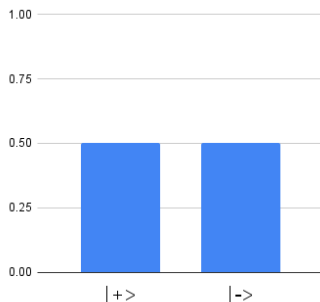
“Projections” of $|\psi\rangle$ onto the position and momentum bases

Knowing one quadrature with certainty means you know little about the other

“Position” Quadrature of $|0\rangle$



“Momentum” Quadrature of $|0\rangle$



The Wigner Function: A Helpful Visual Tool



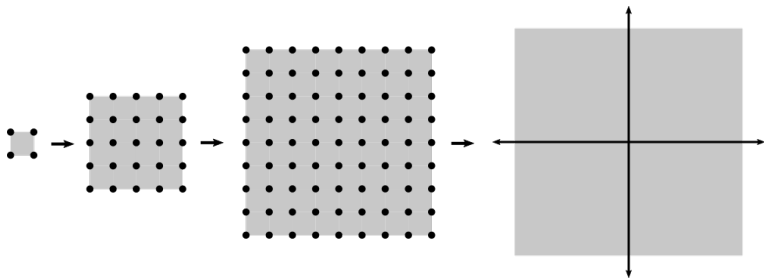
The Wigner Function: Properties

A “Quasiprobability distribution” (can be negative)

To determine the probability of $|n\rangle$, we sum over all spikes with “position” coordinate $|n\rangle$ (same thing for “momentum” basis)

Normalized (all spikes sum to 1)

What happens when we take the limit as $d \rightarrow \infty$?



Continuous Variable Quantum Computing (CV)

Infinitely many (position) basis states $|q\rangle$

Note that $|q\rangle$ and $|q + \varepsilon\rangle$ are orthogonal!

Fourier conjugate basis (momentum): $|p\rangle$

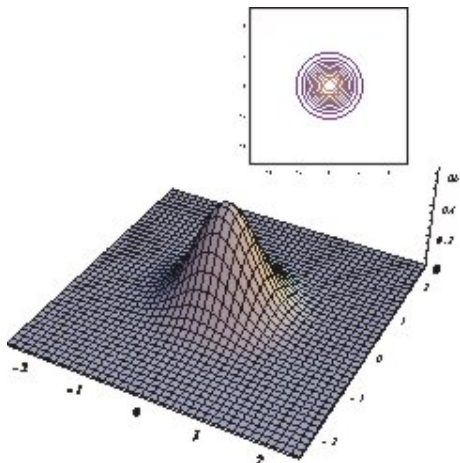
One more basis that's completely new: the number basis, $|n\rangle$

Perfect spikes are no longer feasible, best we can hope for is Gaussians

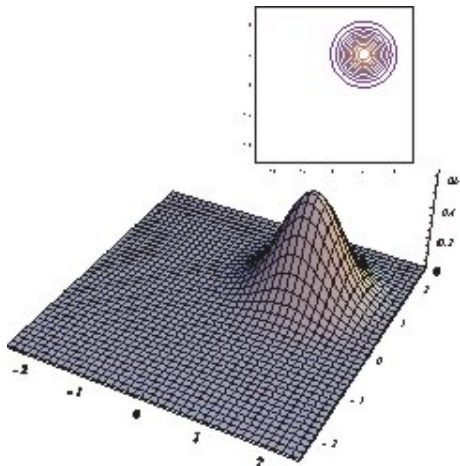
Coherent states:

$$|\alpha\rangle = \frac{1}{\sqrt{e^{|\alpha|^2}}} \sum_{n=0}^{\infty} \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

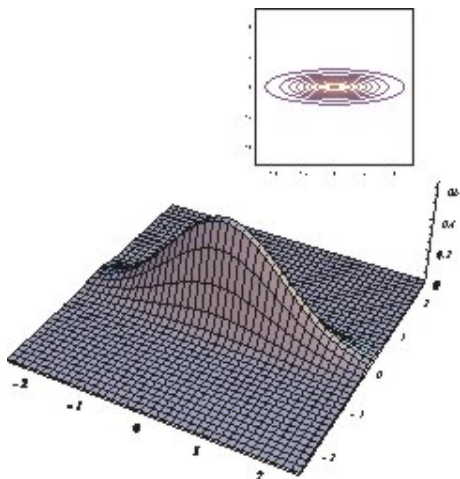
The CV Wigner Function: Vacuum State $|0\rangle$



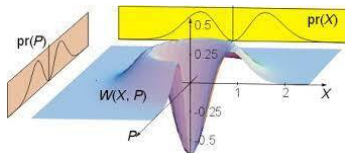
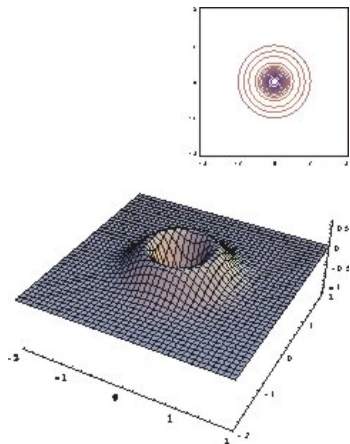
The CV Wigner Function: Coherent State $|\alpha\rangle$



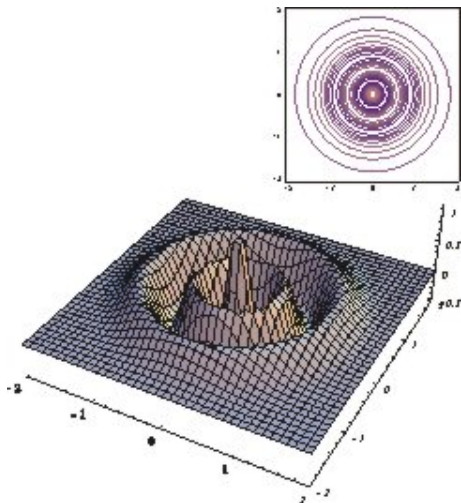
The CV Wigner Function: Squeezed Vacuum



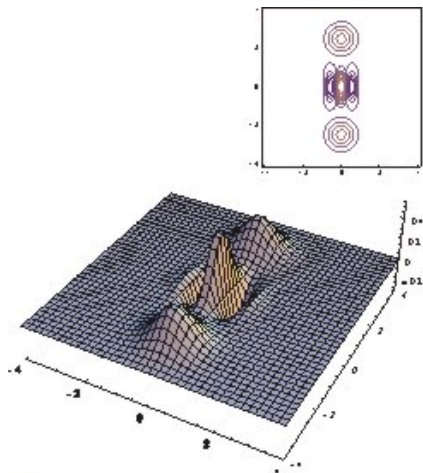
The CV Wigner Function: Fock State $|1\rangle$ (one photon)



The CV Wigner Function: Fock State $|4\rangle$ (four photons)



The CV Wigner Function: Cat State



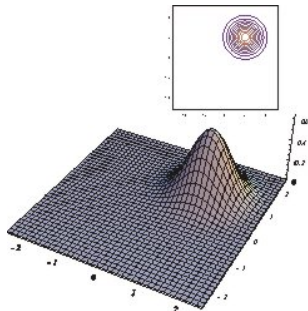
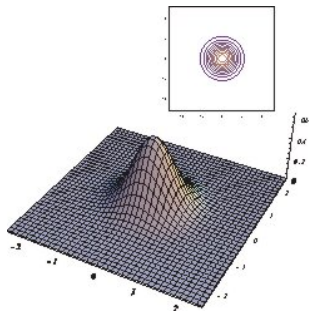
$$|\Psi\rangle = |\alpha\rangle + |-\alpha\rangle$$

Displacement Operator

Displacement operator: $D(\alpha) = \exp(\alpha \hat{a} - \alpha^* \hat{a}^\dagger)$

$D(\alpha) |0\rangle = |\alpha\rangle$

$D(\alpha) |\beta\rangle = |\alpha + \beta\rangle$



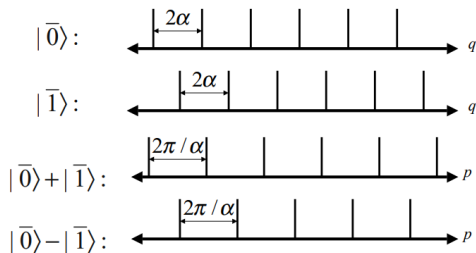
The Ideal GKP Code

Designed to correct small shift errors: $|\delta_q| < \sqrt{\pi}/2$ and $|\delta_p| < \sqrt{\pi}/2$

Note: for large errors, need qubit ECC on top

$$|0_L\rangle \propto \sum_{s=-\infty}^{\infty} |q = 2s\sqrt{\pi}\rangle$$

$$|1_L\rangle \propto \sum_{s=-\infty}^{\infty} |q = (2s + 1)\sqrt{\pi}\rangle$$

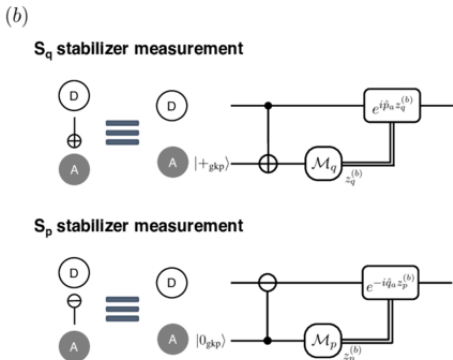
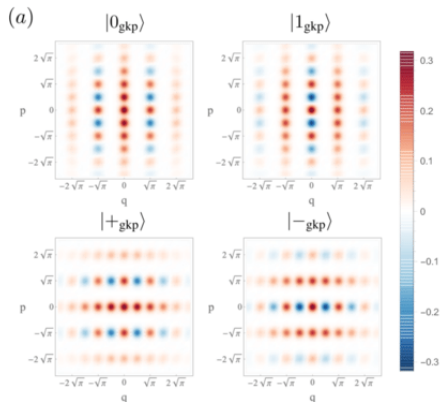


What's the point?

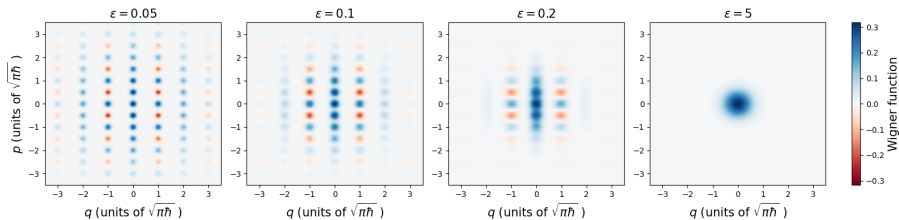
An entirely new kind of error: continuous rather than discrete
Small deviations lead to orthogonal states, unlike with stabilizer codes
Unlike \mathbb{F}_d , has no “wrap-around,” so we have to get creative to find states which have simple stabilizers
GKP Codes provide a helpful source of non-Gaussianity to Gaussian Optical Computing

GKP Stabilizers

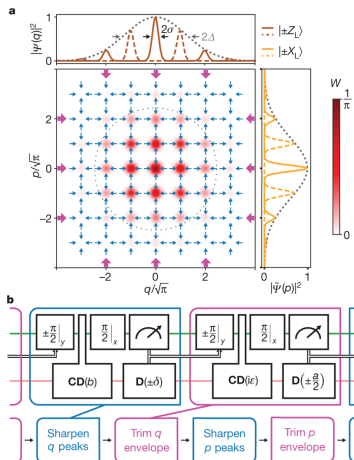
$$S_q = D(i\sqrt{2\pi}), S_p = D(\sqrt{2\pi})$$



Why can't it be ideal?



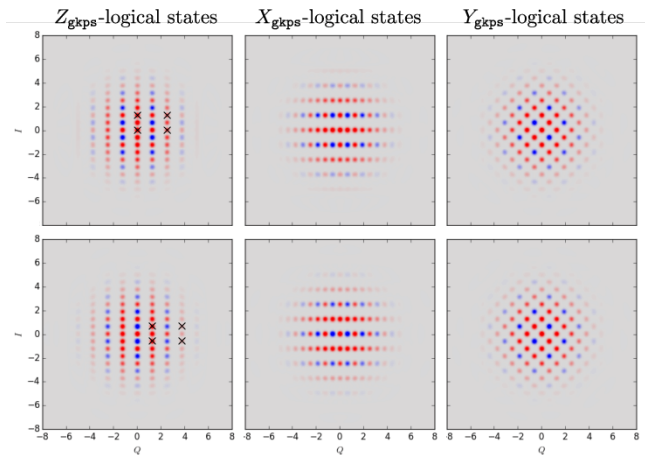
Quadratures, for reference



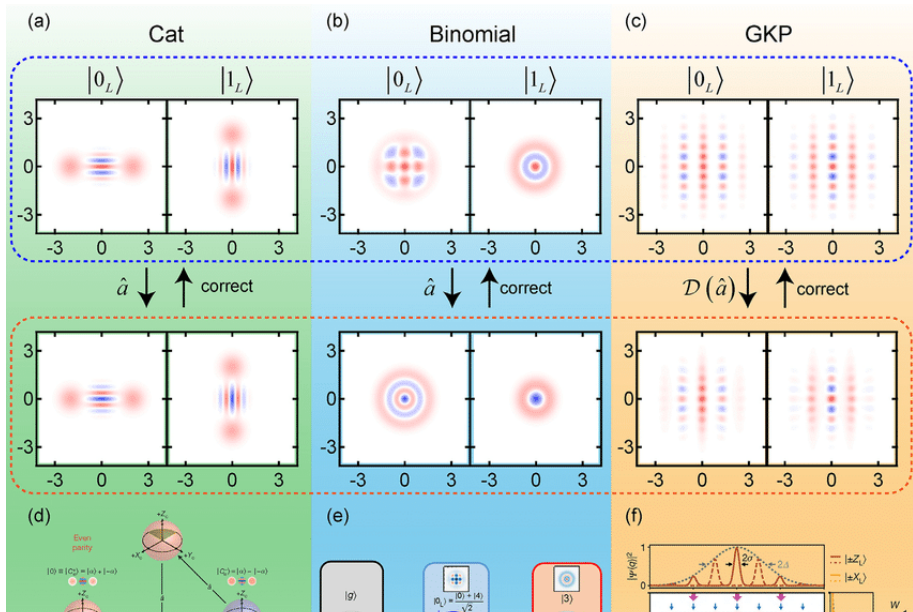
CV Paulis Acting on GKP Code States

$$X = D(i\sqrt{\pi/2}), \quad Z = D(\sqrt{\pi/2}), \quad Y = D(\sqrt{\pi/2} + i\sqrt{\pi/2})$$

Note: Paulis commute!



Other Notable Bosonic Codes



Universal Quantum Computation with Continuous-Variable Cluster States <https://arxiv.org/pdf/quant-ph/0605198.pdf>

All-Gaussian universality and fault tolerance with the Gottesman-Kitaev-Preskill code

<https://arxiv.org/pdf/1903.00012.pdf>

Time-Domain Multiplexed 2-Dimensional Cluster State: Universal Quantum Computing Platform

<https://arxiv.org/pdf/1903.03918.pdf>

Blueprint for a Scalable Photonic Fault-Tolerant Quantum Computer

<https://arxiv.org/pdf/2010.02905v2.pdf>